

**Locke Labs**

*for the common defense*

# New Tools for STEM, Cyber, and Makers

[www.lockelabs.net](http://www.lockelabs.net)

## Overview

- Motivation and Rationale
  - Execute Java source code directly on hardware
  - Concept inspired in part by modular features of Java 9
- Demo Configuration and Slides
  - Embedded Hardware
  - Host configuration
- Caveats
  - Proof of concept, necessary but not sufficient capabilities
    - Memory access, memory allocation and constraints, process interrupts
  - “Execution environment” is not a JVM
- Workflow and Package Structure
- Embedded Code Examples
  - Java main, memory allocation, a SoC module, memory access, interrupts
  - Memory corruption due to stack or heap overflow is currently prevented. Current heap protection approach is presented.
- Discussion


## Motivation and Rationale

- Currently we have large numbers of cyber vulnerabilities and attacks
  - At the same time, we have an increase in the number of people interested in STEM, cyber technology, and makers interested in electronics
- Suggesting that these 3 communities have a similar requirement
  - *How to more easily experiment with the interaction between hardware and software*
- This proof of concept demonstrates that the Java language and pending changes (modularity) have several advantages over traditional embedded programming (C and flavors of Unix)
  - Reduce the attack surface by reducing the number of lines of code executing
  - Stronger typing
  - More consistent memory constraints
  - Per TIOBE, the most popular programming language
  - Reduce the effort of setting up a cross-platform toolchain

## Demo Slides

- Demo Java application utilizes timers, interrupts, and General Purpose Input Output to blink LEDs on a fixed frequency
- Embedded Hardware
  - Initially targeting a Beagle Bone Black board with a TI SoC (AM3358B) with an ARM Cortex-A8 MPU
  - SoC includes:
    - UART
    - Dual Mode Timer
    - Interrupt Controller
    - General Purpose Input Output
    - Power, Reset, and Clock Management
    - Programmable Real-Time Unit and Industrial Communication Subsystem (dual 32-bit RISC cores)
    - Enhanced Direct Memory Access
    - 3-port gigabit ethernet switch
    - Pulse Width Modulation Subsystem
    - USB
    - I2C
    - Controller Area Network (CAN)
    - Multichannel Serial Port Interface (McSPI)
- Host configuration
  - 2010 MacBook Pro
  - Version 4.0.2 of 'screen' terminal emulator
  - USB to TTL Serial Cable and Drivers to BBB Console Serial UART

## Start the runtime, then disable Timers

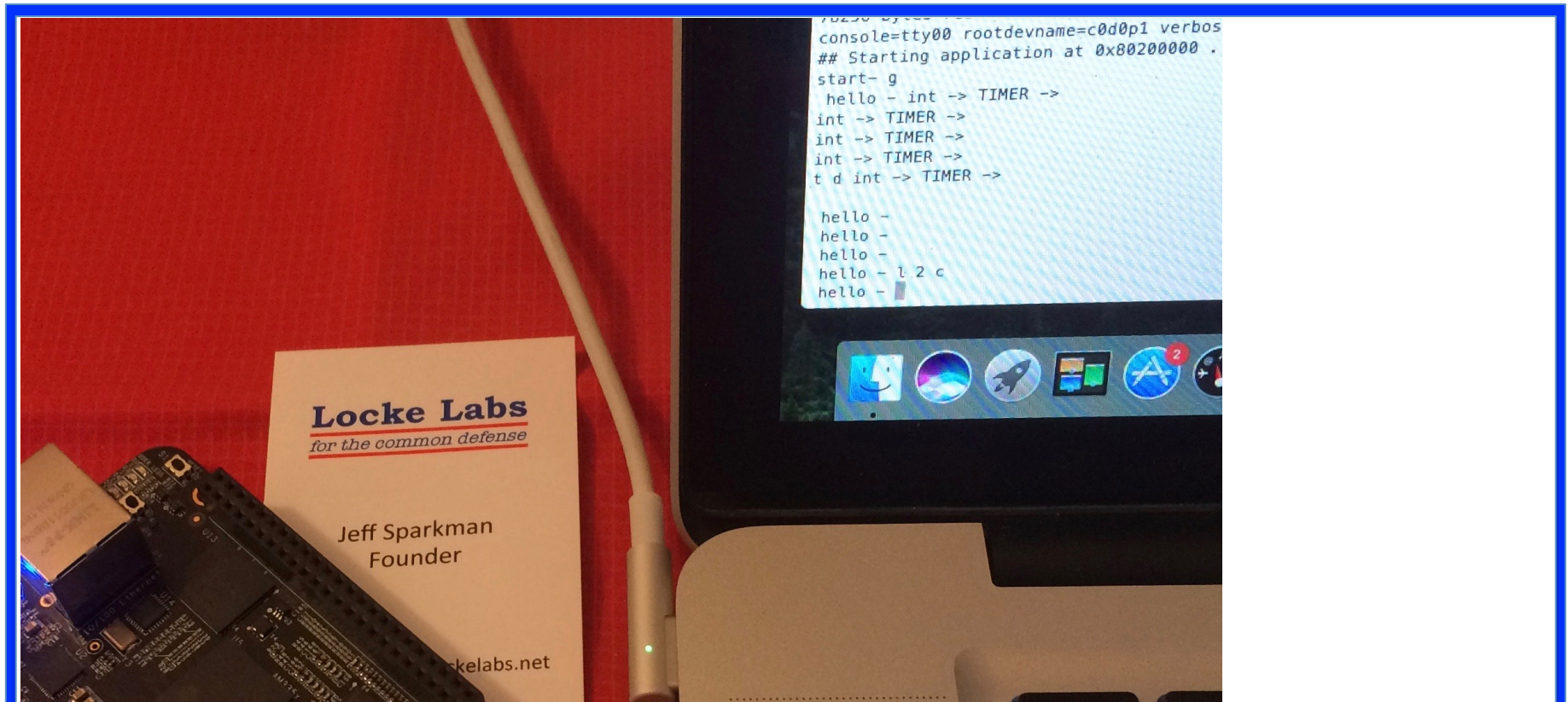


- Runtime waits for 'g' command to run
- Hardcoded to start 2 sec timer. Timer interrupt service routine advances to the next LED
  - 'int' in output denotes that INTC generated the ARM exception
  - 'TIMER' denotes that the interrupt request was generated by the timer
- Timer Disable ('t d') command stops the timer

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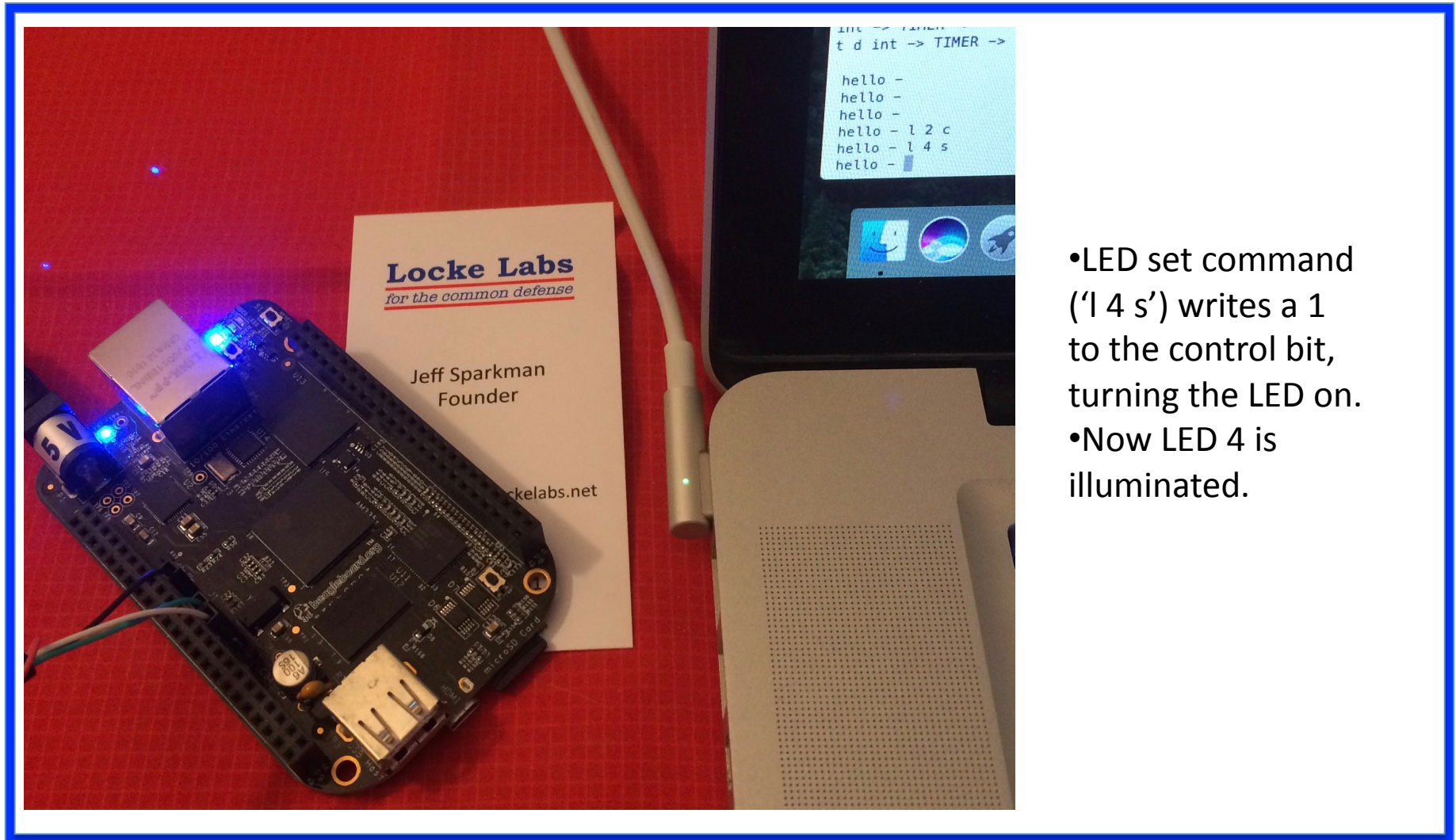
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## Interactively Turn a LED Off



- On previous slide, a single LED was illuminated (LED 2)
- LED clear command ('l 2 c') writes 0 to the control bit, turning the LED off

## Interactively Turn a LED On

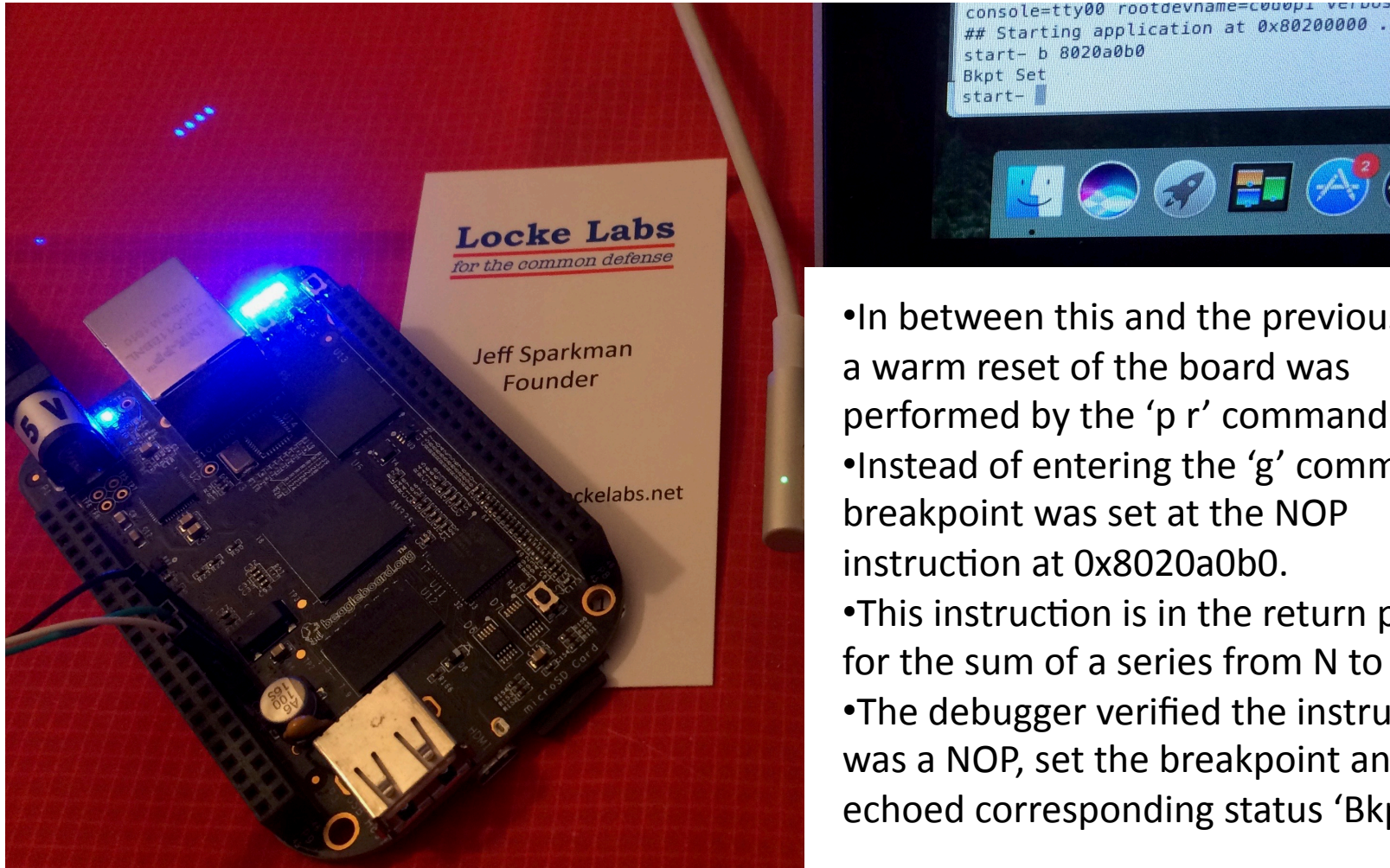


- LED set command ('1 4 s') writes a 1 to the control bit, turning the LED on.
- Now LED 4 is illuminated.

- Java code also implements a simple command line debugger that interactively provides limited (only on NOP) breakpoints, with the ability to display:
  - registers
  - memory contents at address
  - call stack
  - Memory contents of method variables



## Currently No Pause, set an initial Breakpoint

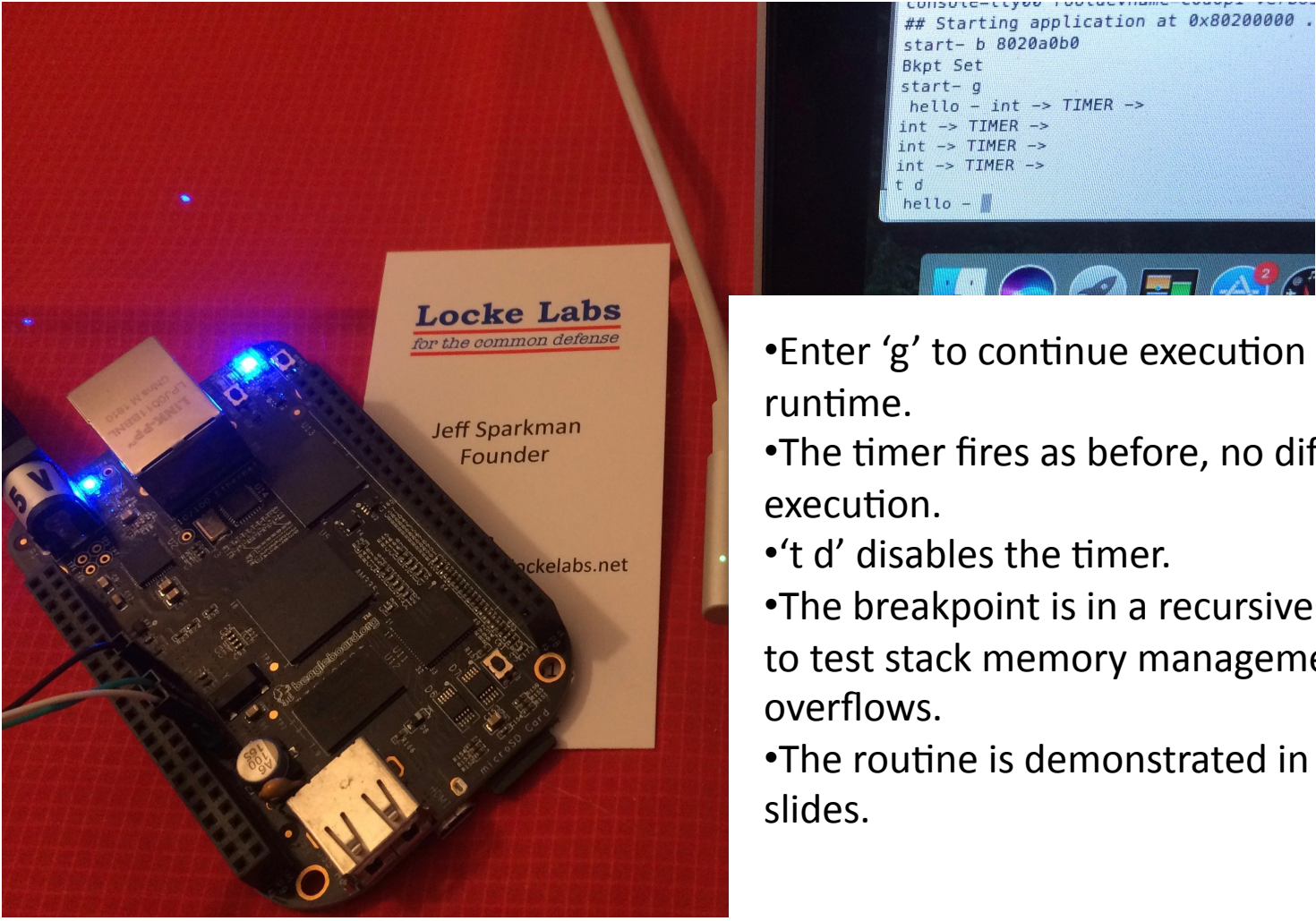


The image shows a Raspberry Pi Zero board with a USB drive and a power source connected. A small card with the Locke Labs logo and "Jeff Sparkman Founder" is placed next to it. To the right, a terminal window shows boot logs and a debugger interface with a breakpoint set at 0x8020a0b0.

```
console=tty00 rootdevname=c000p1 ver=000
## Starting application at 0x80200000 .
start- b 8020a0b0
Bkpt Set
start-
```

- In between this and the previous slide, a warm reset of the board was performed by the 'p r' command.
- Instead of entering the 'g' command, a breakpoint was set at the NOP instruction at 0x8020a0b0.
- This instruction is in the return path for the sum of a series from N to 1.
- The debugger verified the instruction was a NOP, set the breakpoint and echoed corresponding status 'Bkpt Set'.

## Breakpoint is not set in Timer processing

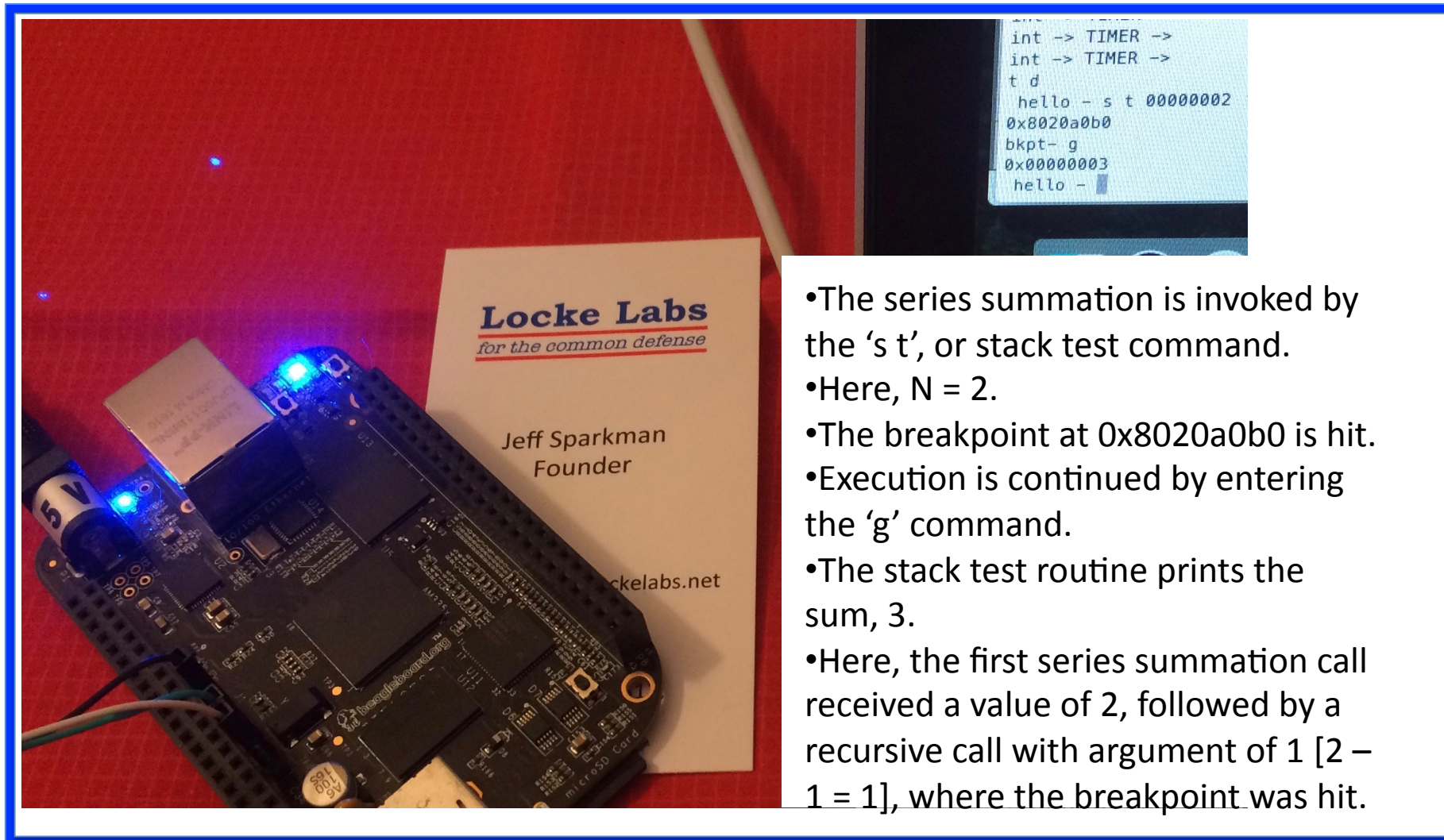


The photograph shows a Raspberry Pi Zero board with a USB drive and a power source. A business card for Locke Labs is placed next to it. The card reads: "Locke Labs for the common defense", "Jeff Sparkman Founder", and "lockelabs.net". An inset image shows a terminal window with the following output:

```
console-tyoo root@evmname-000p1 ~#  
## Starting application at 0x80200000 .  
start- b 8020a0b0  
Bkpt Set  
start- g  
hello - int -> TIMER ->  
int -> TIMER ->  
int -> TIMER ->  
int -> TIMER ->  
t d  
hello -
```

- Enter 'g' to continue execution of the runtime.
- The timer fires as before, no difference in execution.
- 't d' disables the timer.
- The breakpoint is in a recursive routine used to test stack memory management and overflows.
- The routine is demonstrated in following slides.

## Hit a Breakpoint, But then Continue



- The series summation is invoked by the 's t', or stack test command.
- Here, N = 2.
- The breakpoint at 0x8020a0b0 is hit.
- Execution is continued by entering the 'g' command.
- The stack test routine prints the sum, 3.
- Here, the first series summation call received a value of 2, followed by a recursive call with argument of 1 [2 - 1 = 1], where the breakpoint was hit.

## Display Stack Frames and Local Variables

```
console=tty00 rootdevname=c0d0p1 verbos
## Starting application at 0x80200000 .
start- b 8020a0b0
Bkpt Set
start- g
  hello - int -> TIMER ->
int -> TIMER ->
int -> TIMER ->
int -> TIMER ->
t d
  hello - s t 00000002
0x8020a0b0
bkpt- g
0x00000003
  hello - s t 00000003
0x8020a0b0
bkpt- f l
0x80211798
0x80211784
ls frames
index - 0x00000000
#vars - 0x00000002
rtnAd - 0x8020a0fc

index - 0x00000001
#vars - 0x00000002
rtnAd - 0x8020a0fc

index - 0x00000002
#vars - 0x00000002
rtnAd - 0x8020a394

index - 0x00000003
#vars - 0x00000004
rtnAd - 0x8020acd8

index - 0x00000004
#vars - 0x00000006
rtnAd - 0x80202098

bkpt- □
```

- Several lines down on the left, the stack test is repeated with the command 's t 00000003'.
- The breakpoint is hit, and all the current stack frames are listed with the 'f l' command.
- For each frame, the number of local variables and return address are listed
- A few lines from the top on the right, the register values at the breakpoint are displayed with the 'dr' command.
- On the lower half of the right, the local variables of several of the stack frames are displayed via the 'f v l 0000000i' command, where "i" is 0, 1, and 2.

```
index - 0x00000004
#vars - 0x00000006
rtnAd - 0x80202098

bkpt- dr
cpsr- 0x60000193
R0: 0x00000001
R1: 0x00000001
R2: 0x80211000
R3: 0x80200000
R4: 0x80211798
R5: 0x80211784
R6: 0x80211798
R7: 0x9ff63c99
R8: 0x80211800
R9: 0x80211000
RA: 0x00000000
RB: 0x00000001
RC: 0x00000000
RD: 0x8021173c
RE: 0x8020a0fc
bkpt- f v l 00000000
0x80211798
0x80211784
ls vars
index - 0x00000000
val - 0x00000001

index - 0x00000001
val - 0x00000001

bkpt- f v l 00000001
0x80211798
0x80211784
ls vars
index - 0x00000000
val - 0x00000002

index - 0x00000001
val - 0x00000001

bkpt- f v l 00000002
0x80211798
0x80211784
ls vars
index - 0x00000000
val - 0x00000003

index - 0x00000001
val - 0x802123a8

bkpt- □
```

## Caveats (1 of 2)

- Proof of concept, necessary but not sufficient capabilities to be a compliant JVM
  - Memory access, memory allocation and constraints, process interrupts
- “Execution environment” is not a JVM
  - Only executes native code statically linked with the execution environment
  - Currently a very small subset of the Java language features are implemented
    - Static classes, methods, primitive fields (int and boolean), dynamic allocation of character arrays (no memory reclamation)
    - Utilizing custom annotations to integrate link time information, Java source, and a limited amount of hard coded native assembly source
    - No objects, exceptions, or threads yet
  - Have not created a target Java platform, using project specific packages for defining and testing the current capability of heap and stack errors.

## Caveats (2 of 2)

- Java Specs
  - Java Language Specification, Java SE 8 Edition, 2015-02-13
  - Java Virtual Machine Specification, Java SE 8 Edition, 2015-02-13
- Status of JVM Instruction implementation
  - Implemented to varying degrees - aload, arraylength, astore, bipush, caload, castore, dup, getstatic, goto, iadd, iand, iconst, if\_icmpge, ifeq, iflt, iinc, iload, imul, invokestatic, ireturn, istore, isub, ldc, newarray, putstatic, return
  - Currently no implementation includes – any array other than char array, double instructions, float instructions, related to objects such as invokespecial or invokevirtual, switch statements such as lookupswitch or tableswitch, synchronization such as monitorenter or monitorexit

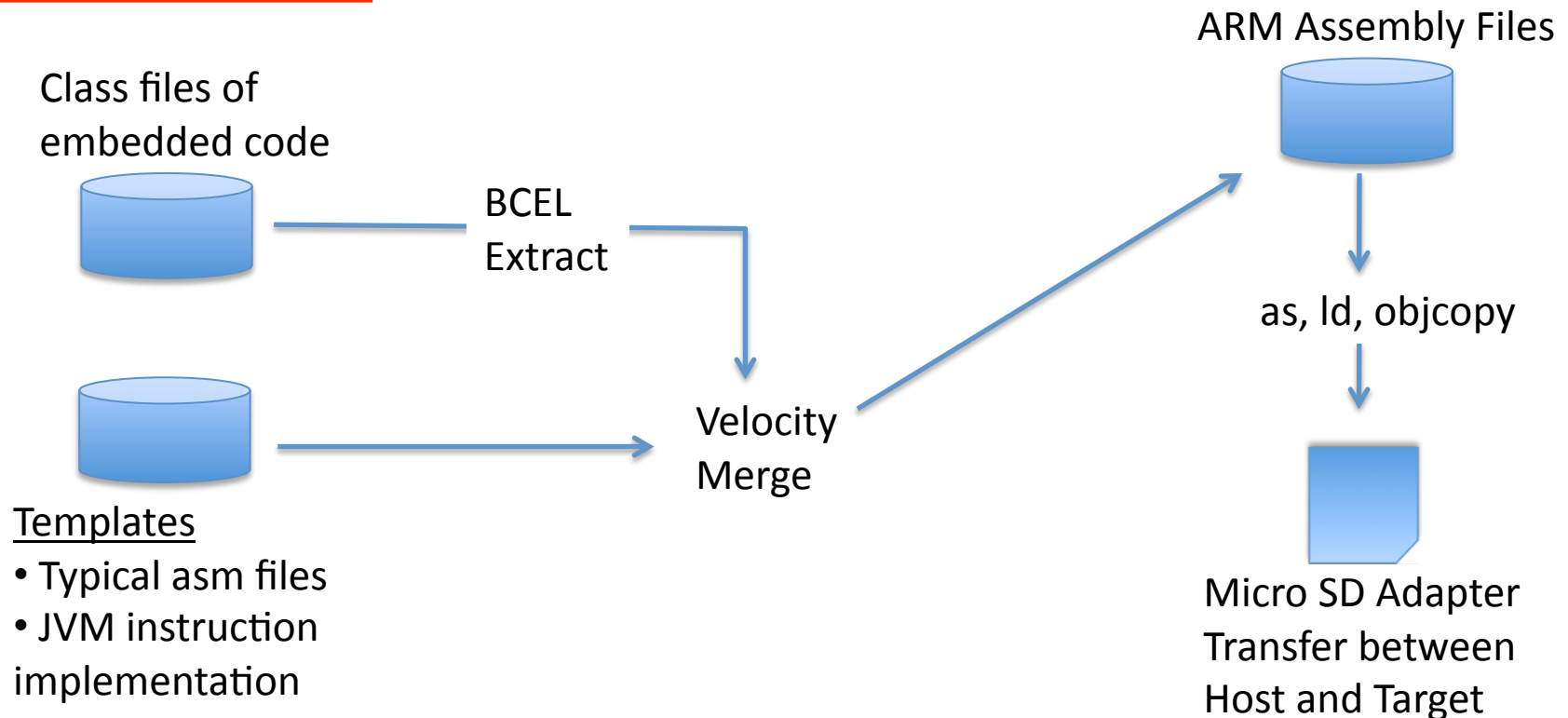
## Workflow (1 of 2)

- Cross Platform Toolchain
  - Cross compiled Minix ARM port to BeagleBone Black
  - <http://wiki.minix3.org/doku.php?id=developersguide:minixonarm>
  - From this, I am using u-boot and cross-platform GNU binutils – as, ld, objcopy, and objdump
- Target Build Process
  - Netbeans compile of embedded Java and native generation tool (also Java)
  - Run the native generation tool
    - Depends on BCEL and Velocity and generates ARM assembly
    - Running with JDK 8
  - Run as, ld, objcopy, and objdump
    - Ld is generating ELF, objcopy is transforming to binary
    - Objdump generates asm of linked executable to manually lookup addresses for breakpoints

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## Workflow (2 of 2)



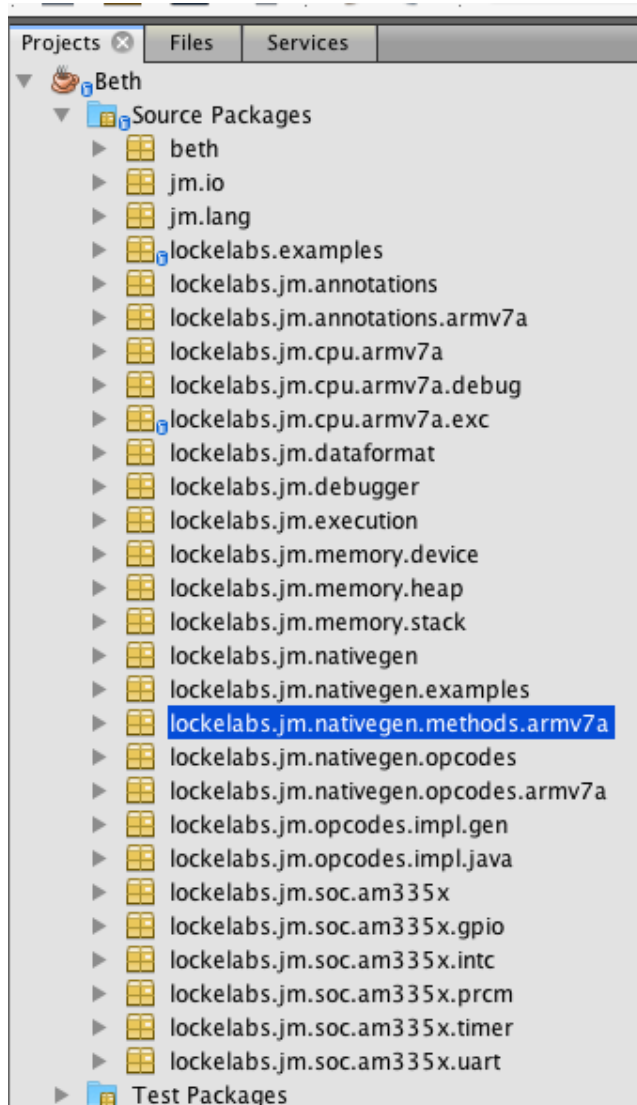
- This is a notional diagram of the native code generation process
- The flow 'Templates, Merge, Assembly File' is repeated for a variety of files and types.
- Some of these file types are the entry point to the executable, assembly routines that process ARM exceptions, templates for implementation of JVM instructions, etc.
- This native generation approach is very straightforward, no optimization is performed to reduce code size, number of operand stack accesses, etc



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## Package Structure



- Non-compliant placeholder namespace for Stack and Heap errors (jm.lang)
- User application code (lockelabs.examples)
- Support code, either offline or on target (eg, lockelabs.jm.annotations, lockelabs.jm.cpu, lockelabs.jm.memory.heap)
- Ahead of time generation of native code (lockelabs.jm.nativegen)
- ‘Drivers’ for modules on the SoC (lockelabs.jm.soc)

- Java main, memory allocation, a SoC module, memory access, interrupts
- Memory limit implementations
- *The following slides illustrate code that runs on the target.*
- *Information from the target build process is included with these slides to illustrate what was required to execute the Java source code.*

## Java main - Initialization

```
62
63 char[] helloPrompt = new char[]{' ', 'h', 'e', 'l', 'l', 'o', ' ', '-', ' '};
64
65 // char[] lsrString = new char[HexString.requiredBufferLength];
66
67 char[] counterString = new char[HexString.requiredBufferLength];
68
69 char[] eol = new char[]{'\n', '\r'};
70
71 int uartLineStatusRegister;
72
73 WatchDogTimer.disable();
74
75 GenlPurposeInputOutput.initialize();
76 DualModeTimer.initialize();
77 InterruptController.initialize();
78
79 DualModeTimer.startTimer();
80
81 // Adder adder = new Adder(3, 4);
82
83 int counter = 0;
84 while (true) {
85
```

- Line 63 illustrates allocation and initialization of char array. Will look at implementation in following slides.
- Lines 73 – 79 illustrate initializing modules on the TI SoC (eg, GPIO, Timers, Interrupt Controller). Examine Interrupt Controller initialization in following slides.
- Line 84 starts the main loop of the main method. Illustrated on next slide.

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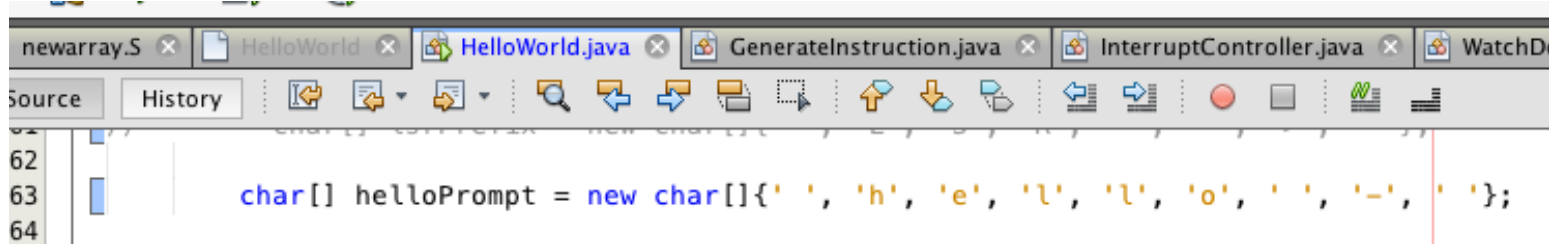
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## Java main - Loop

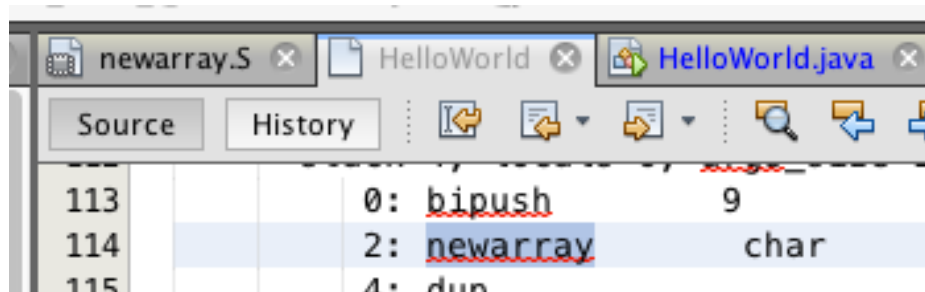
```
82
83     int counter = 0;
84     while (true) {
85
86
87         Instance.printf(uart0BaseAddress, helloPrompt);
88         Instance.readLine(uart0BaseAddress, fromUart);
89         //
90         // InterruptController.printInfo();
91
92         GenlPurposeInputOutput.processCommand(fromUart);
93
94         DualModeTimer.processCommand(fromUart);
95
96         PrmDevice.processCommand(fromUart);
97
98         HeapManager.processCommand(fromUart);
99
100        StackManager.processCommand(fromUart);
101
102        //         HexString.convert(adder.add(), counterString);
103        //
104        //         Instance.printf(uart0BaseAddress, counterString);
105        //         Instance.printf(uart0BaseAddress, eol);
106
107        counter++;
108    }
109
110
```

- Line 88 reads characters and carriage return entered on Mac keyboard and transmitted over USB-to-TTL to UART (aka console port) on Beagle Bone Black.
- Lines 92 – 100 pass the current 'command' to each of the processCommand static methods.

## Memory Allocation (1 of 3)



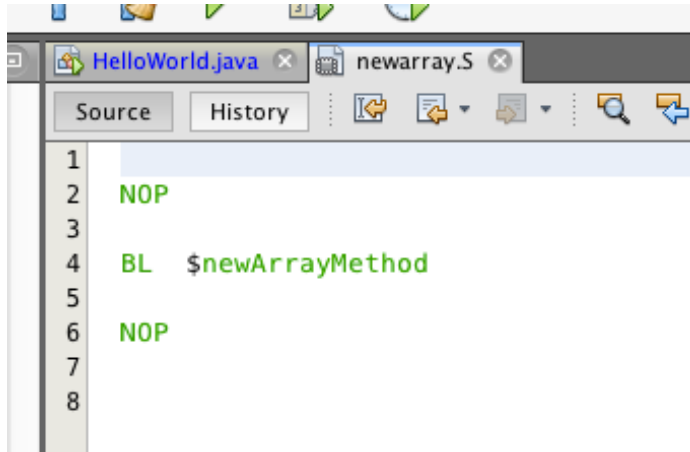
```
62 |
63 |     char[] helloPrompt = new char[]{' ', 'h', 'e', 'l', 'l', 'o', ' ', '-', ' '};
64 |
```



113	0:	bipush	9
114	2:	<b>newarray</b>	char
115	4:	dup	

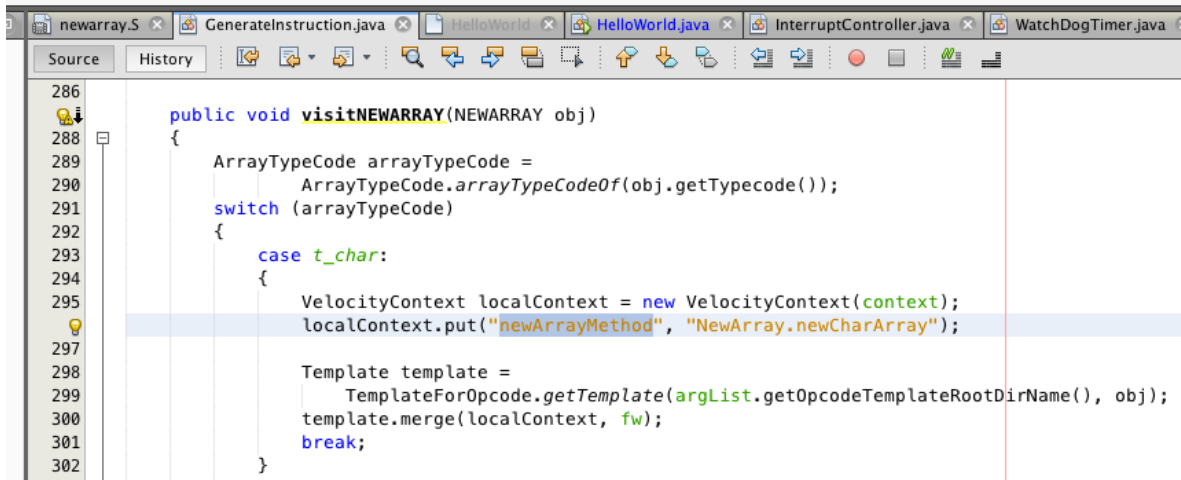
- Code above is from user main.
- At left are the disassembled JVM instructions for the allocation of the char array above.
- On the next slide, the current JVM instruction (newarray) is transformed to native code.

## Memory Allocation (2 of 3)

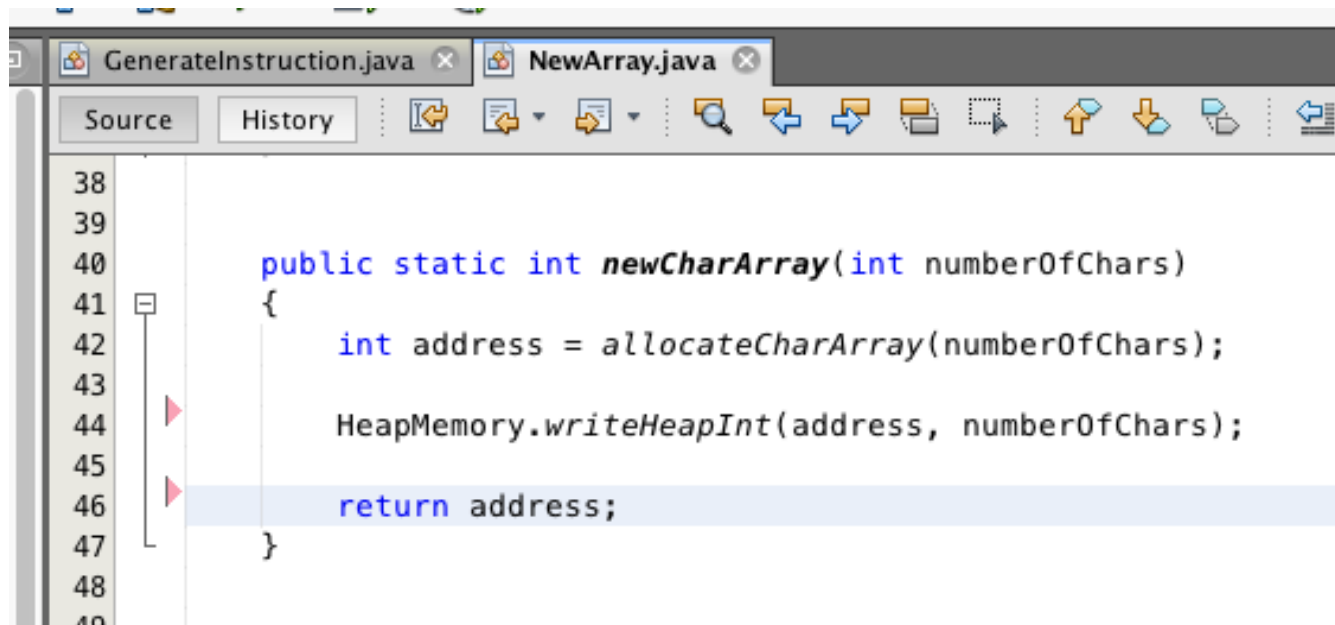


```
1
2  NOP
3
4  BL  $newArrayMethod
5
6  NOP
7
8
```

- Code below only runs during native code generation.
- Each JVM instruction has a corresponding template. At left is the template for newarray.
- During code generation, template is merged with relevant data from BCEL and written to current asm file. In this case, the HelloWorld.S file.
- Below, the variable newArrayMethod in the template at left is replaced with the class and static method (NewArray.newCharArray on line 296). This method is shown on the next slide.



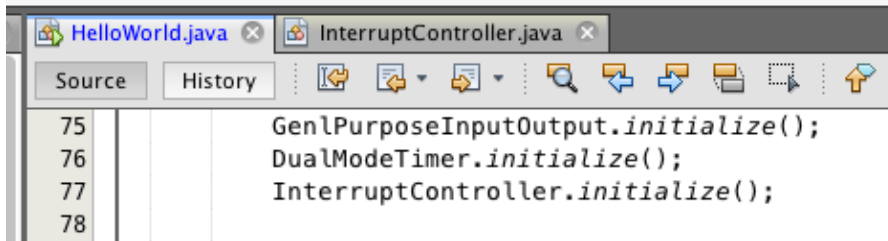
```
286
287
288 public void visitNEWARRAY(NEWARRAY obj)
289 {
290     ArrayTypeCode arrayTypeCode =
291         ArrayTypeCode.arrayTypeCodeOf(obj.getTypeCode());
292     switch (arrayTypeCode)
293     {
294     case t_char:
295     {
296         VelocityContext localContext = new VelocityContext(context);
297         localContext.put("newArrayMethod", "NewArray.newCharArray");
298
299         Template template =
300             TemplateForOpcodes.getTemplate(argList.getOpcodesTemplateRootDirName(), obj);
301         template.merge(localContext, fw);
302         break;
303     }
304     }
```



```
38
39
40 public static int newCharArray(int numberOfChars)
41 {
42     int address = allocateCharArray(numberOfChars);
43
44     HeapMemory.writeHeapInt(address, numberOfChars);
45
46     return address;
47 }
48
49
```

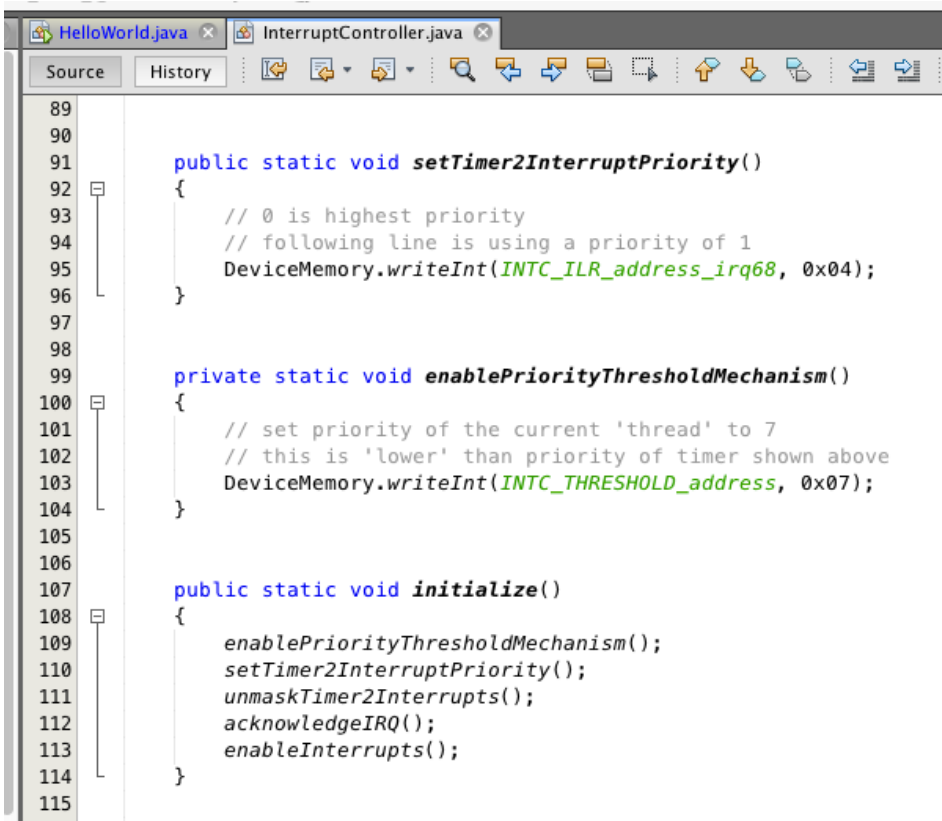
- This method runs only on the target and allocates char arrays from the heap and initializes each array with the length of the array. The presence of the length enables index range checking to verify that the bounds of the array are not being exceeded by application code.

## SoC Module – Interrupt Controller



```
75 GenlPurposeInputOutput.initialize();
76 DualModeTimer.initialize();
77 InterruptController.initialize();
78
```

- Lines 75 – 77 at left are from the Java main method. One of the methods, `InterruptController.initialize`, is shown below.



```
89
90
91 public static void setTimer2InterruptPriority()
92 {
93     // 0 is highest priority
94     // following line is using a priority of 1
95     DeviceMemory.writeInt(INTC_ILR_address_irq68, 0x04);
96 }
97
98
99 private static void enablePriorityThresholdMechanism()
100 {
101     // set priority of the current 'thread' to 7
102     // this is 'lower' than priority of timer shown above
103     DeviceMemory.writeInt(INTC_THRESHOLD_address, 0x07);
104 }
105
106
107 public static void initialize()
108 {
109     enablePriorityThresholdMechanism();
110     setTimer2InterruptPriority();
111     unmaskTimer2Interrupts();
112     acknowledgeIRQ();
113     enableInterrupts();
114 }
115
---
```

- The code at left calls the `DeviceMemory` class to write the memory mapped control registers of the `InterruptController`.



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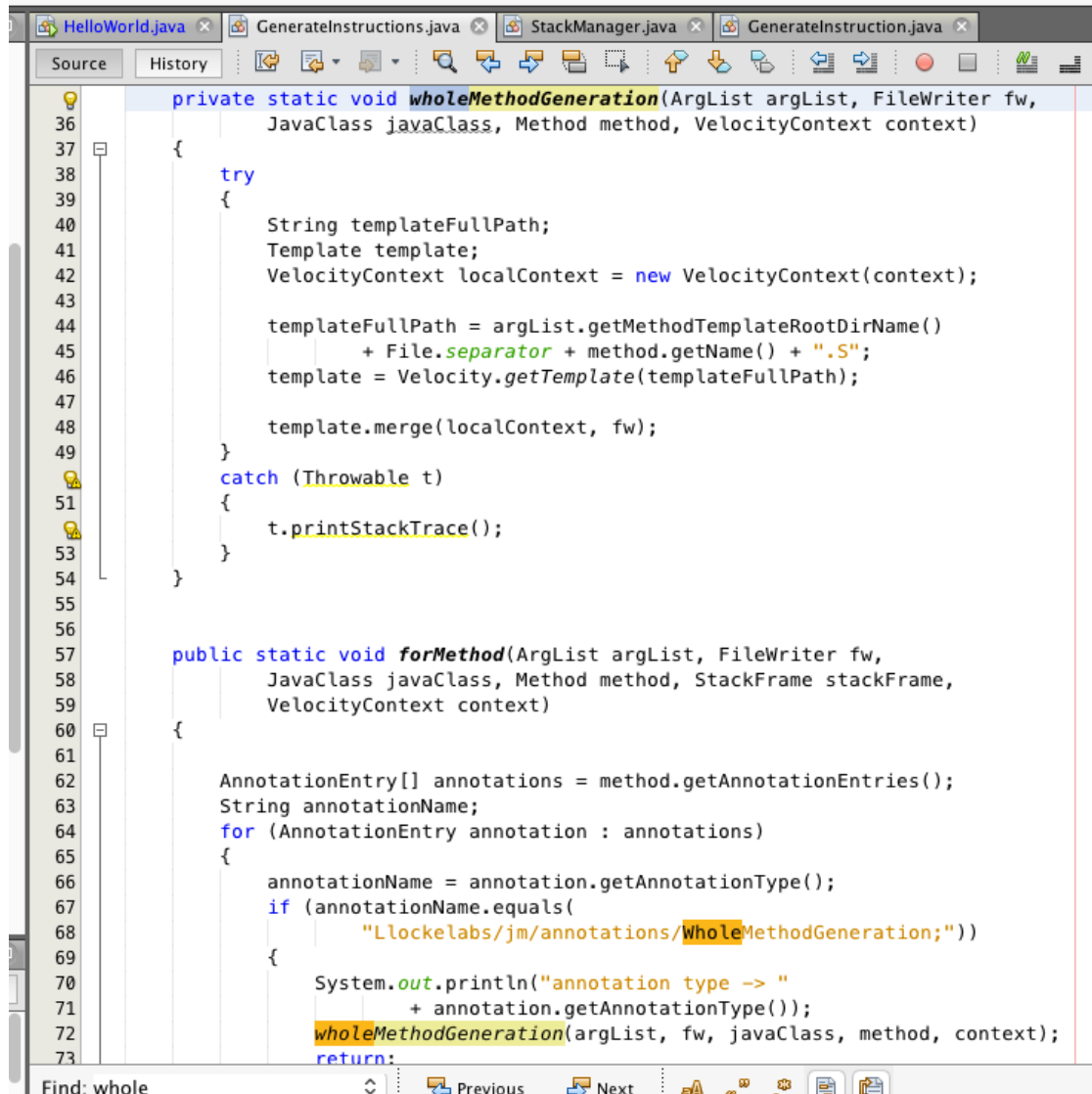
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## Memory Access (1 of 3)

```
7  |  */
8  |  package lockelabs.jm.annotations;
9  |
10 |  /**
11 |   *
12 |   * @author jeff
13 |   */
14 |  public @interface WholeMethodGeneration {
15 |
16 |  }
17 |
```

```
8  |  package lockelabs.jm.memory.device;
9  |
10 |  import lockelabs.jm.annotations.WholeMethodGeneration;
11 |
12 |  /**
13 |   *
14 |   * @author jeff
15 |   */
16 |  public class DeviceMemory {
17 |
18 |      @WholeMethodGeneration
19 |      public static int readInt(int address)
20 |      {
21 |          return 0;
22 |      }
23 |
24 |      @WholeMethodGeneration
25 |      public static void writeInt(int address, int value)
26 |      {
27 |      }
28 |
29 |  }
30 |
```

- In the code at left, each method is decorated with the WholeMethodGeneration annotation.
- During the native code generation process, any method with this annotation is generated by reading one template for the entire method instead of iterating through the JVM instructions generated by the Java compiler for the method.
- An example of this process is shown on the next slide.



```
private static void wholeMethodGeneration(ArgList argList, FileWriter fw,
    JavaClass javaClass, Method method, VelocityContext context)
{
    try
    {
        String templateFullPath;
        Template template;
        VelocityContext localContext = new VelocityContext(context);

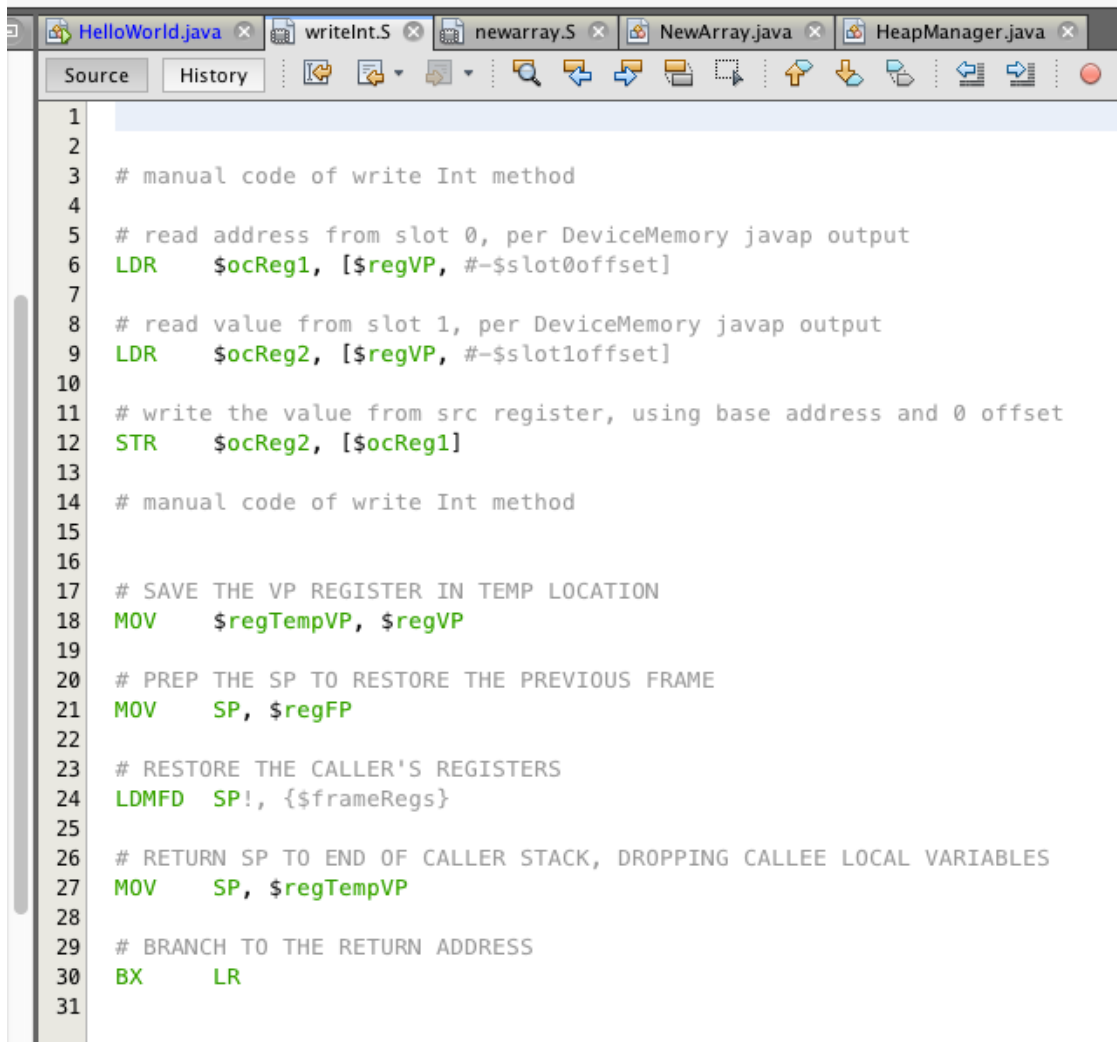
        templateFullPath = argList.getMethodTemplateRootDirName()
            + File.separator + method.getName() + ".S";
        template = Velocity.getTemplate(templateFullPath);

        template.merge(localContext, fw);
    }
    catch (Throwable t)
    {
        t.printStackTrace();
    }
}

public static void forMethod(ArgList argList, FileWriter fw,
    JavaClass javaClass, Method method, StackFrame stackFrame,
    VelocityContext context)
{
    AnnotationEntry[] annotations = method.getAnnotationEntries();
    String annotationName;
    for (AnnotationEntry annotation : annotations)
    {
        annotationName = annotation.getAnnotationType();
        if (annotationName.equals(
            "Lockelabs/jm/annotations/WholeMethodGeneration;"))
        {
            System.out.println("annotation type -> "
                + annotation.getAnnotationType());
            wholeMethodGeneration(argList, fw, javaClass, method, context);
        }
    }
}
```

- Shown at line 57, forMethod generates the native assembly code for an embedded Java source code method.
- If the Java method has the WholeMethodGeneration annotation, the template is loaded and merged with the current context (shown in lines 36 – 54).
- The result is written to the ARM assembly file being generated for the current Java class.

## Memory Access (3 of 3)



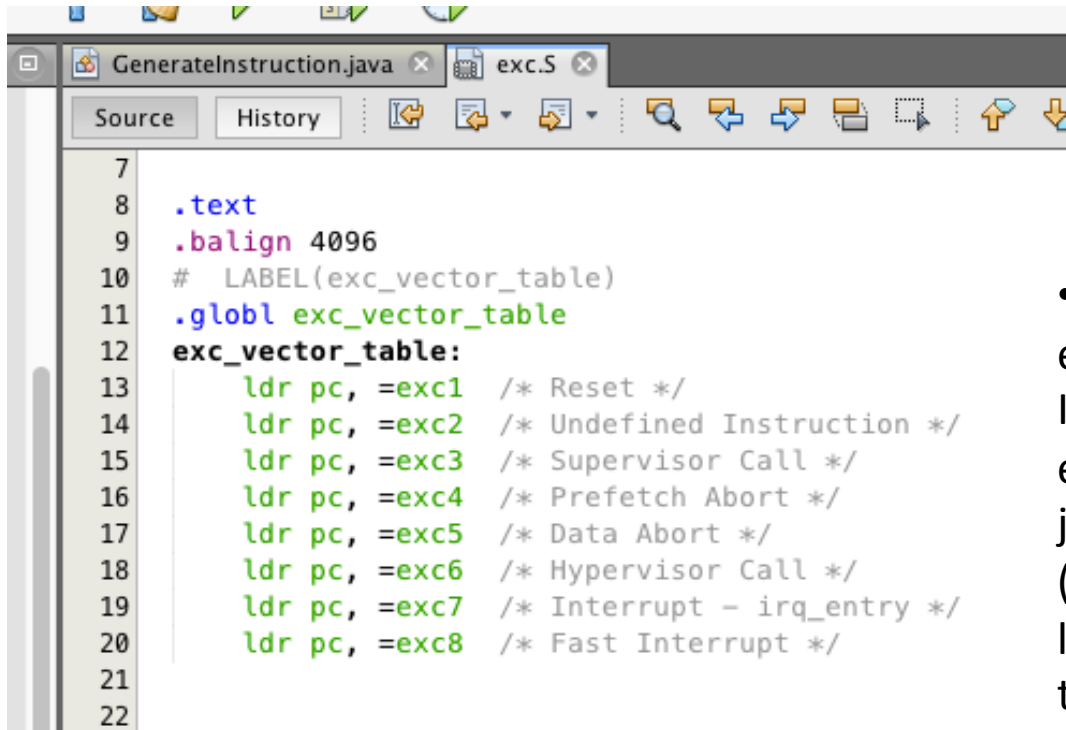
```
1  
2  
3 # manual code of write Int method  
4  
5 # read address from slot 0, per DeviceMemory javap output  
6 LDR    $ocReg1, [$regVP, #-$slot0offset]  
7  
8 # read value from slot 1, per DeviceMemory javap output  
9 LDR    $ocReg2, [$regVP, #-$slot1offset]  
10  
11 # write the value from src register, using base address and 0 offset  
12 STR    $ocReg2, [$ocReg1]  
13  
14 # manual code of write Int method  
15  
16  
17 # SAVE THE VP REGISTER IN TEMP LOCATION  
18 MOV    $regTempVP, $regVP  
19  
20 # PREP THE SP TO RESTORE THE PREVIOUS FRAME  
21 MOV    SP, $regFP  
22  
23 # RESTORE THE CALLER'S REGISTERS  
24 LDMFD  SP!, {$frameRegs}  
25  
26 # RETURN SP TO END OF CALLER STACK, DROPPING CALLEE LOCAL VARIABLES  
27 MOV    SP, $regTempVP  
28  
29 # BRANCH TO THE RETURN ADDRESS  
30 BX     LR  
31
```

- The template at left is not the whole method for writeInt.
- There is a preMethod template that implements stack overflow checks and initializes the stack frame for the current method.
- The native generation process needs some refactoring. You can see at left that each method is responsible for popping the current frame.
- Template variables are used here as well so that I can easily change register convention when needed.

## Interrupts (1 of 4)

```
LDR R0, =exc_vector_table
MCR p15, 0, R0, c12, c0, 0
```

During startup of the execution environment, initialize the ARM Vector Base Address Register



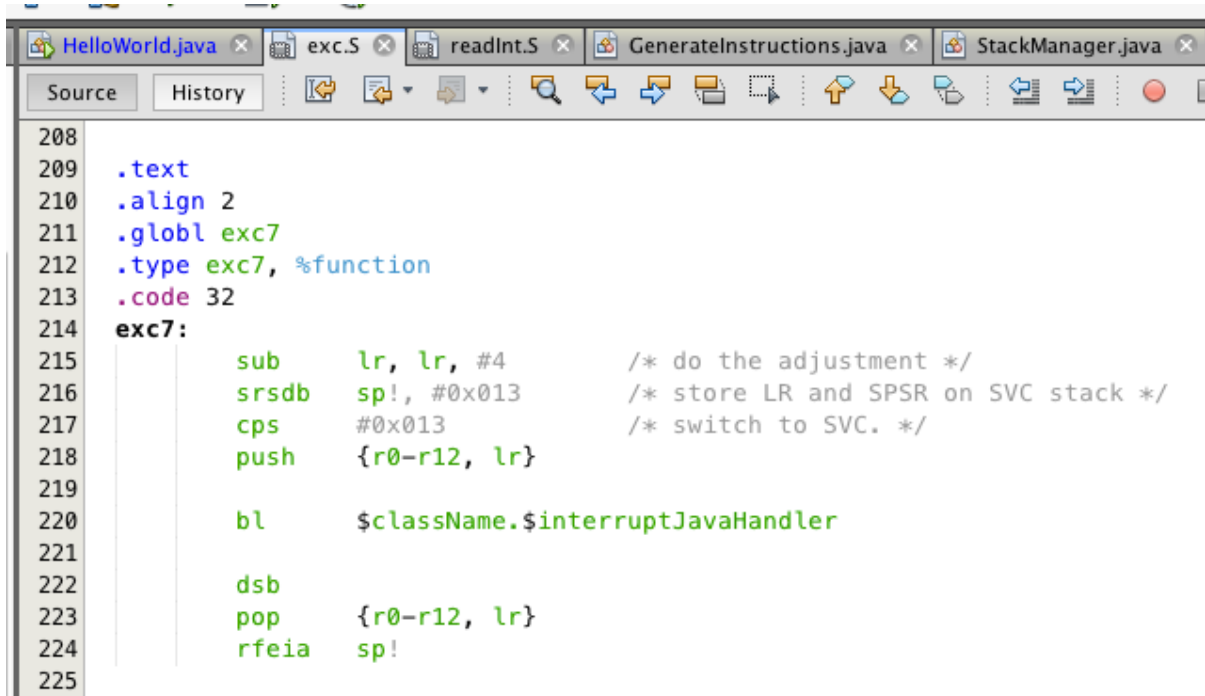
```
7
8 .text
9 .balign 4096
10 # LABEL(exc_vector_table)
11 .globl exc_vector_table
12 exc_vector_table:
13     ldr pc, =exc1 /* Reset */
14     ldr pc, =exc2 /* Undefined Instruction */
15     ldr pc, =exc3 /* Supervisor Call */
16     ldr pc, =exc4 /* Prefetch Abort */
17     ldr pc, =exc5 /* Data Abort */
18     ldr pc, =exc6 /* Hypervisor Call */
19     ldr pc, =exc7 /* Interrupt - irq_entry */
20     ldr pc, =exc8 /* Fast Interrupt */
21
22
```

- On the ARM MPU, when one of the exceptions (Reset, Data Abort, Interrupt from Interrupt Controller, etc) occurs, instruction execution jumps to the corresponding handler (Reset : exc1, Interrupt : exc7) by loading the PC with the address of that handler.

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## Interrupts (2 of 4)



```
208
209 .text
210 .align 2
211 .globl exc7
212 .type exc7, %function
213 .code 32
214 exc7:
215     sub    lr, lr, #4           /* do the adjustment */
216     srsdb  sp!, #0x013        /* store LR and SPSR on SVC stack */
217     cps    #0x013            /* switch to SVC. */
218     push  {r0-r12, lr}
219
220     bl    $className.$interruptJavaHandler
221
222     dsb
223     pop  {r0-r12, lr}
224     rfeia sp!
225
```

- The merged version of this file, which is part of the execution environment, is how Java source code is called when an interrupt occurs.

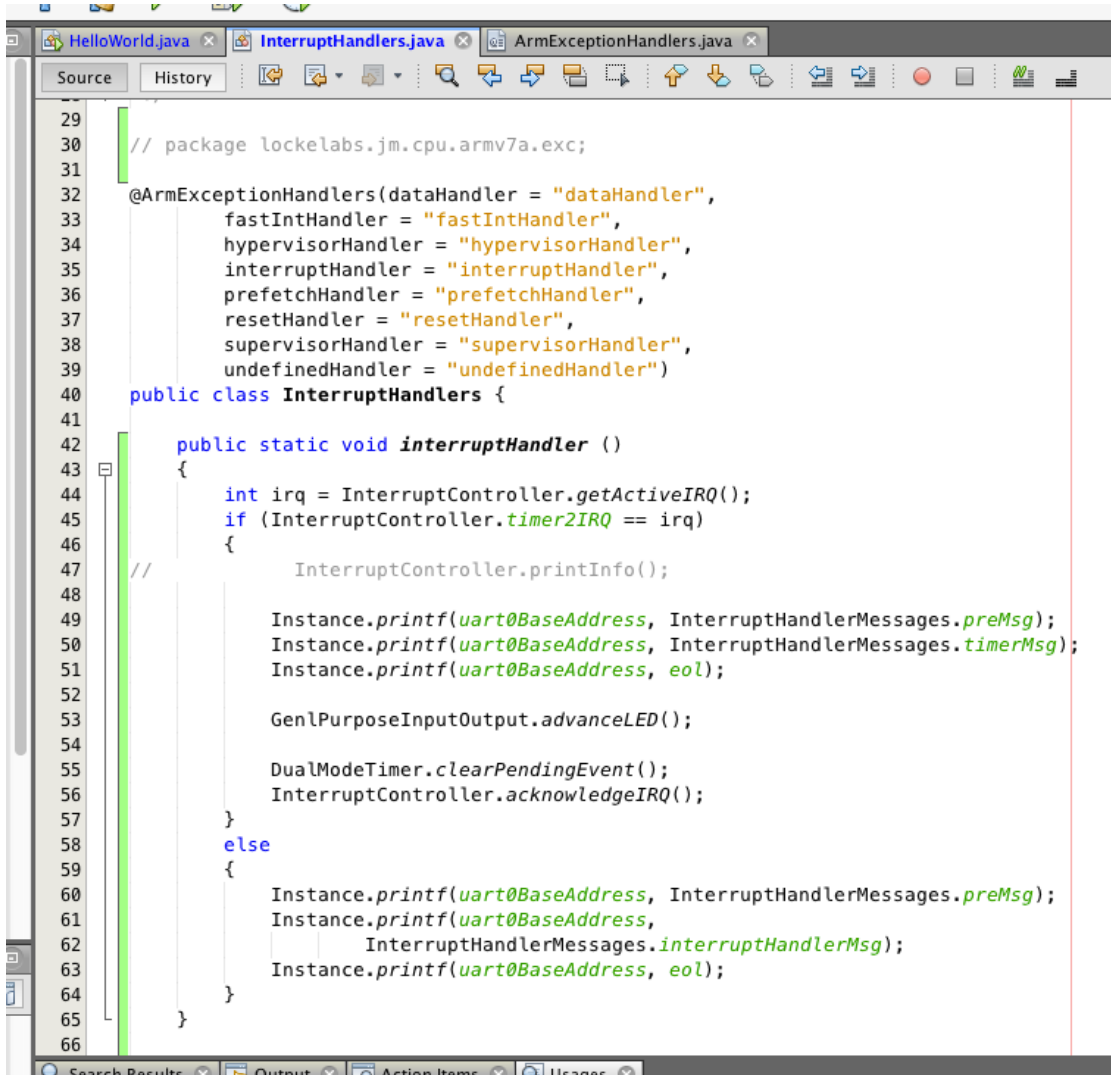
- The file shown above, exc.S, is the 'template' version.
- Line 220 is an example of two Velocity 'variables' in this template.
- At native code generation time, \$className and \$interruptJavaHandler are replaced with their actual names as supplied by Java source code. Example of this on the next slide, line 157 and method setMethodNames.

## Interrupts (3 of 4)

```
131
132     private static void installAnyInterruptHandlers(String outDirNode,
133     ArgList argList, JavaClass javaClass, VelocityContext context,
134     GenerationResult result) throws Exception
135     {
136
137         final String fileName = "exc";
138
139         AnnotationEntry[] annotations = javaClass.getAnnotationEntries();
140         String annotationName;
141         for (AnnotationEntry annotation : annotations)
142         {
143             annotationName = annotation.getAnnotationType();
144             if (annotationName.equals(
145                 "Llockelabs/jm/annotations/armv7a/ArmExceptionHandlers;"))
146             {
147                 System.out.println("annotation type -> "
148                     + annotation.getAnnotationType());
149
150                 FileWriter fw = new FileWriter(outDirNode + File.separator +
151                     fileName + ".S");
152
153                 String templateFullPath;
154                 Template template;
155                 VelocityContext localContext = new VelocityContext(context);
156
157                 setMethodNames(javaClass, annotation, localContext);
158
159                 templateFullPath = argList.getMethodTemplateRootDirName()
160                     + File.separator + fileName + ".S";
161                 template = Velocity.getTemplate(templateFullPath);
162
163                 template.merge(localContext, fw);
164                 fw.close();
165             }
166         }
167     }
168 }
```

```
7  L  /*
8  package lockelabs.jm.annotations.armv7a;
9
10 /**
11  * ARM defines the 8 exception handlers listed l
12  * same as Java exceptions. These ARM handlers
13  * interrupt handlers.
14  * @author jeff
15  */
16 public @interface ArmExceptionHandlers {
17
18     String resetHandler();
19
20     String undefinedHandler();
21
22     String supervisorHandler();
23
24     String prefetchHandler();
25
26     String dataHandler();
27
28     String hypervisorHandler();
29
30     String interruptHandler();
31
32     String fastIntHandler();
33
34 }
35 }
```

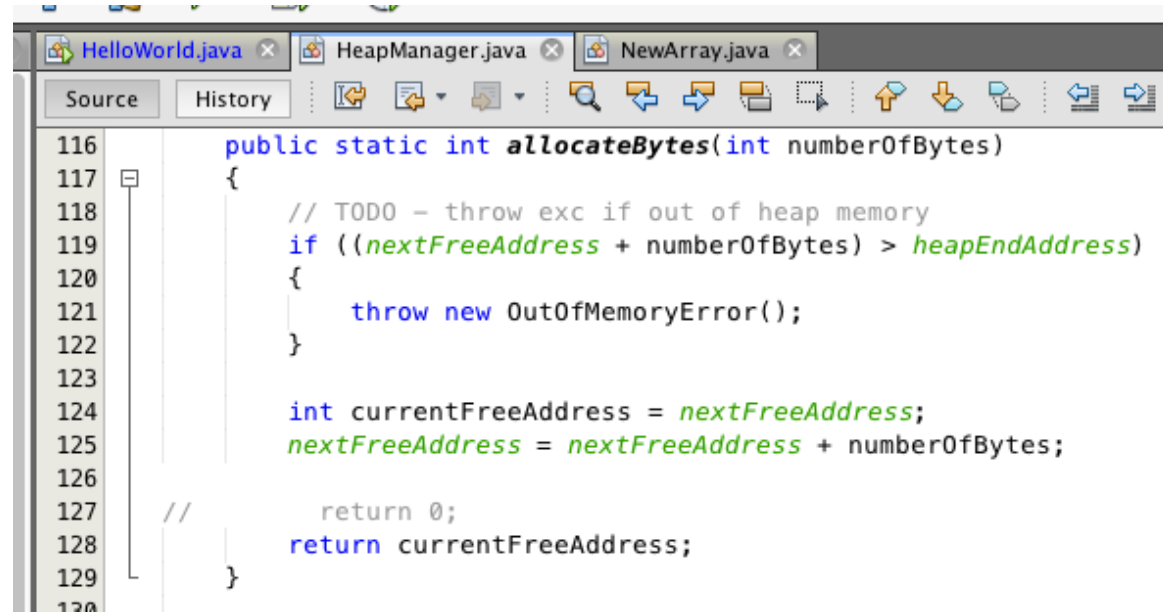
- Both of the files above are relevant only during native code generation.
- The file on the left illustrates reading the template exc.S and generating corresponding merged ARM assembly language file exc.S.



```
29
30 // package lockelabs.jm.cpu.armv7a.exc;
31
32 @ArmExceptionHandler(dataHandler = "dataHandler",
33     fastIntHandler = "fastIntHandler",
34     hypervisorHandler = "hypervisorHandler",
35     interruptHandler = "interruptHandler",
36     prefetchHandler = "prefetchHandler",
37     resetHandler = "resetHandler",
38     supervisorHandler = "supervisorHandler",
39     undefinedHandler = "undefinedHandler")
40 public class InterruptHandlers {
41
42     public static void interruptHandler ()
43     {
44         int irq = InterruptController.getActiveIRQ();
45         if (InterruptController.timer2IRQ == irq)
46         {
47             //
48             InterruptController.printInfo();
49
50             Instance.printf(uart0BaseAddress, InterruptHandlerMessages.preMsg);
51             Instance.printf(uart0BaseAddress, InterruptHandlerMessages.timerMsg);
52             Instance.printf(uart0BaseAddress, eol);
53
54             GenlPurposeInputOutput.advanceLED();
55
56             DualModeTimer.clearPendingEvent();
57             InterruptController.acknowledgeIRQ();
58         }
59         else
60         {
61             Instance.printf(uart0BaseAddress, InterruptHandlerMessages.preMsg);
62             Instance.printf(uart0BaseAddress,
63                 InterruptHandlerMessages.interruptHandlerMsg);
64             Instance.printf(uart0BaseAddress, eol);
65         }
66     }
67 }
```

- This file was rearranged to place relevant details on one screen.
- This illustrates the Java source code that processes an interrupt.
- As shown in previous slides, the ArmExceptionHandler annotation is used during native code generation to insert the name of the Java source methods to call from the execution environment.
- The method interruptHandler is the method invoked when the ARM MPU responds to the Interrupt Controller exception, the exc7 label on a previous slide.

## Memory Limits – Heap (1 of 3)



```
116     public static int allocateBytes(int numberOfBytes)
117     {
118         // TODO - throw exc if out of heap memory
119         if ((nextFreeAddress + numberOfBytes) > heapEndAddress)
120         {
121             throw new OutOfMemoryError();
122         }
123
124         int currentFreeAddress = nextFreeAddress;
125         nextFreeAddress = nextFreeAddress + numberOfBytes;
126
127         //     return 0;
128         return currentFreeAddress;
129     }
130 }
```

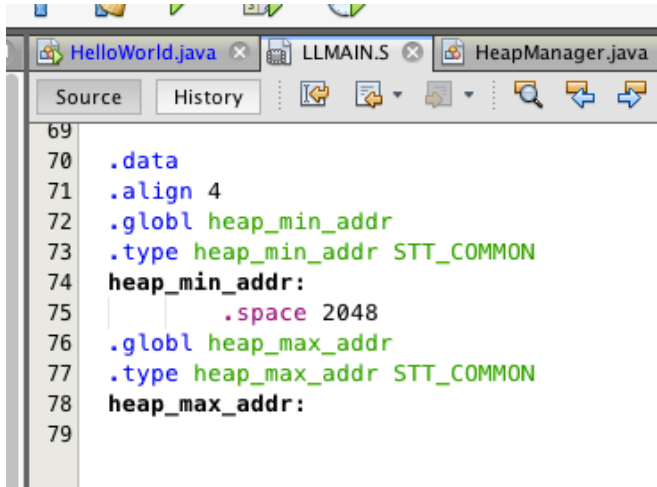
- HeapManager.allocateBytes, shown above, is called in the context of allocating a char array.
- On line 121 above, an OutOfMemoryError exception is thrown when a heap allocation fails.
- The current implementation of new and throwing exceptions is only a proof of concept that illustrates Java detection and halt when stack or heap allocation fails.
- Current implementations of new and throw are not presented.
- Implementation of the heapEndAddress is illustrated on following slides.



# Locke Labs

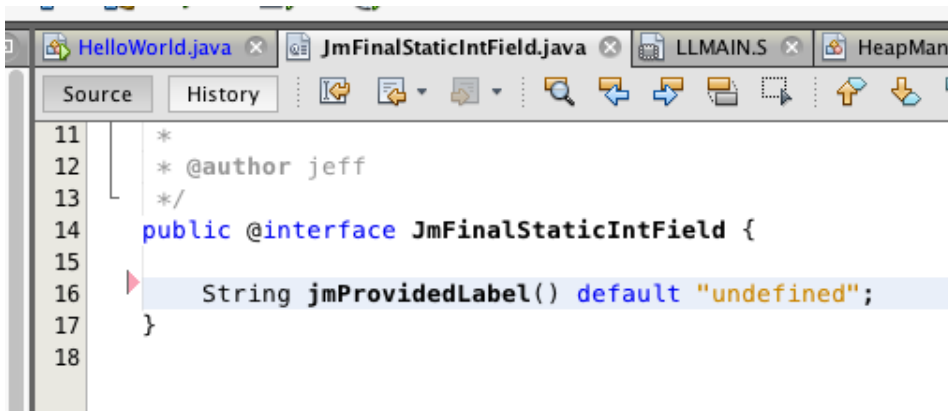
*for the common defense*

## Memory Limits – Heap (2 of 3)



```
69
70 .data
71 .align 4
72 .globl heap_min_addr
73 .type heap_min_addr STT_COMMON
74 heap_min_addr:
75     .space 2048
76 .globl heap_max_addr
77 .type heap_max_addr STT_COMMON
78 heap_max_addr:
79
```

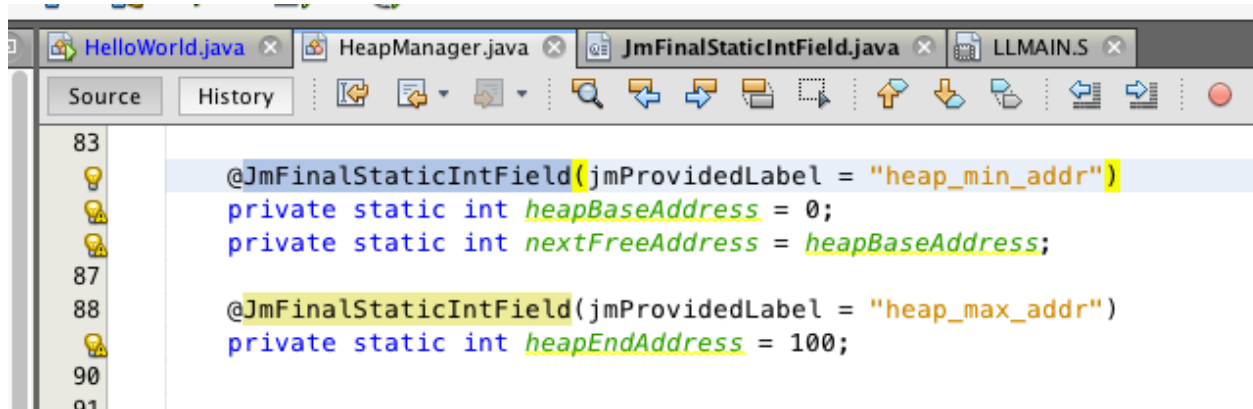
- This slide and the following illustrate how the heap end address is currently integrated with Java source.
- LLMAIN shown at left is the entry point for the executable started by u-boot.
- On line 78, the end address of the heap is statically defined.



```
11
12 *
13 * @author jeff
14 */
15 public @interface JmFinalStaticIntField {
16     String jmProvidedLabel() default "undefined";
17 }
18
```

- The annotation at left is utilized to integrate the assembly language heap end address and the Java source references to the same address.

## Memory Limits – Heap (3 of 3)



```
83 @JmFinalStaticIntField(jmProvidedLabel = "heap_min_addr")
    private static int heapBaseAddress = 0;
    private static int nextFreeAddress = heapBaseAddress;
87
88 @JmFinalStaticIntField(jmProvidedLabel = "heap_max_addr")
    private static int heapEndAddress = 100;
90
91
```

- During class init, the address of the provided label is stored in the annotated int.
- This is implemented with a 'special case' template for the putstatic JVM instruction.
- This special case drops the value provided by the class file and instead uses the address of the label provided by the annotation.

- Working towards a KickStarter campaign for June 2017
  - Prep and release all code as open source, considering a BSD 4-clause license
  - Write a book with 2 general topics
    - Step by step instructions for novice to reproduce the capabilities described here
    - Detailed description of design and implementation
  - Identify a stretch goal of a Java implementation of required GNU binutils. Primarily, as, ld, objcopy, objdump. Believe these would have to be released as GPL.
- Questions

## Backup Slides

## Classes Java main doesn't depend on?

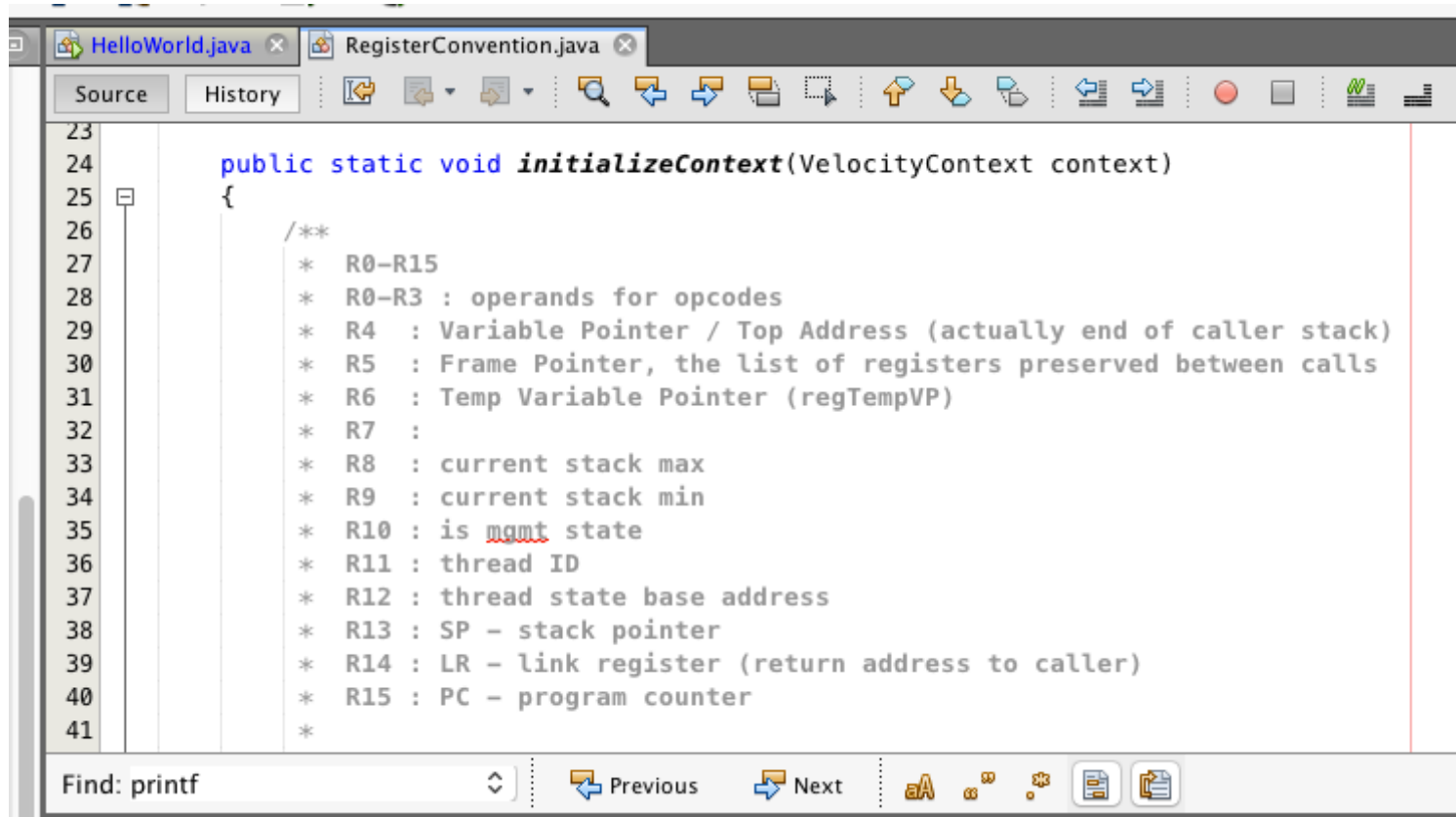
- InterruptHandlers
- HeapManager
- HeapMemory
- NewArray

Native code generation visits all dependencies of Java main and generates corresponding native code. The classes above don't appear as dependencies and therefore have to be included manually in the list of classes to generate.

## How Much 'Plain' Assembly?

- LLMAIN.S – defines the method started by u-boot.
- exc.S – defines the exception vector table and initial service routines.
- jvmMain.S – invokes methods to initialize static data of classes and invokes Java main method.
- Files to read and write system control / status registers : flush caches to implement setting breakpoint, address of instruction fault, read and write int values to memory, etc.

## Register Convention



```
23
24 public static void initializeContext(VelocityContext context)
25 {
26     /**
27     * R0-R15
28     * R0-R3 : operands for opcodes
29     * R4 : Variable Pointer / Top Address (actually end of caller stack)
30     * R5 : Frame Pointer, the list of registers preserved between calls
31     * R6 : Temp Variable Pointer (regTempVP)
32     * R7 :
33     * R8 : current stack max
34     * R9 : current stack min
35     * R10 : is mgmt state
36     * R11 : thread ID
37     * R12 : thread state base address
38     * R13 : SP - stack pointer
39     * R14 : LR - link register (return address to caller)
40     * R15 : PC - program counter
41     *
```

- Some of the above are notional at this point.
- R0-R3, R4, R5 are the ones listed most frequently in the examples.
- R0-R3 referenced as ocReg1 – ocReg3 in templates (oc = op code)
- R4, R5, and LR are currently pushed to stack between calls.

## Notional Stack Contents

	R4 - VP - end of caller stack (Var Ptr)
zzz	
aaa	
bbb	
ccc	
ddd	
eee	
fff	
	Local Variables
LR	
R5	R5 - FP - caller's local variables (Frame Ptr)
R4	
ggg	
hhh	
iii	
jjj	
kkk	
lll	
mmm	
nnn	SP - Callee local stack